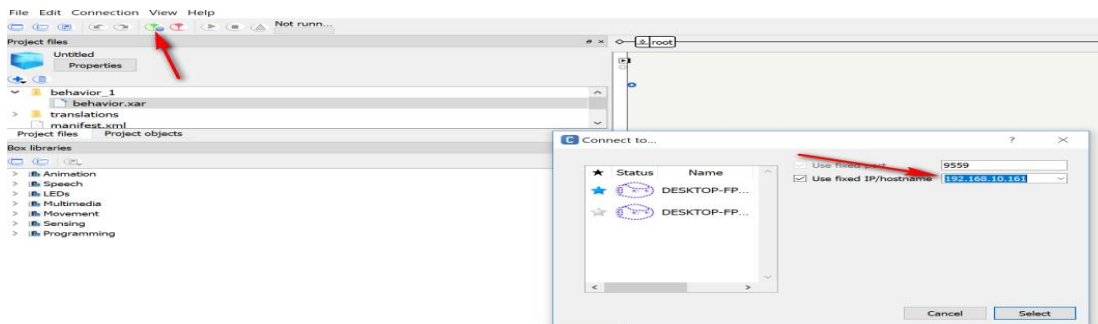


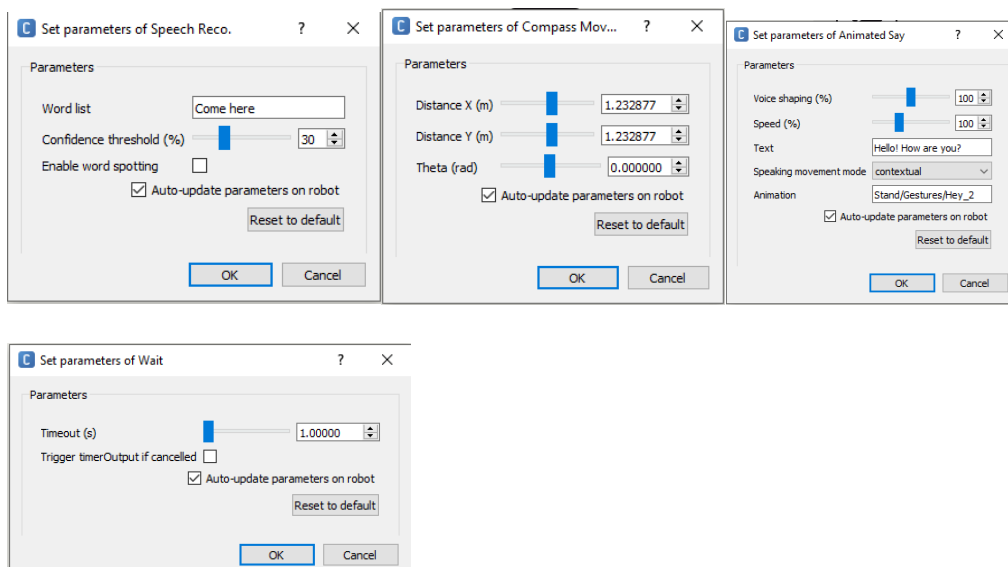
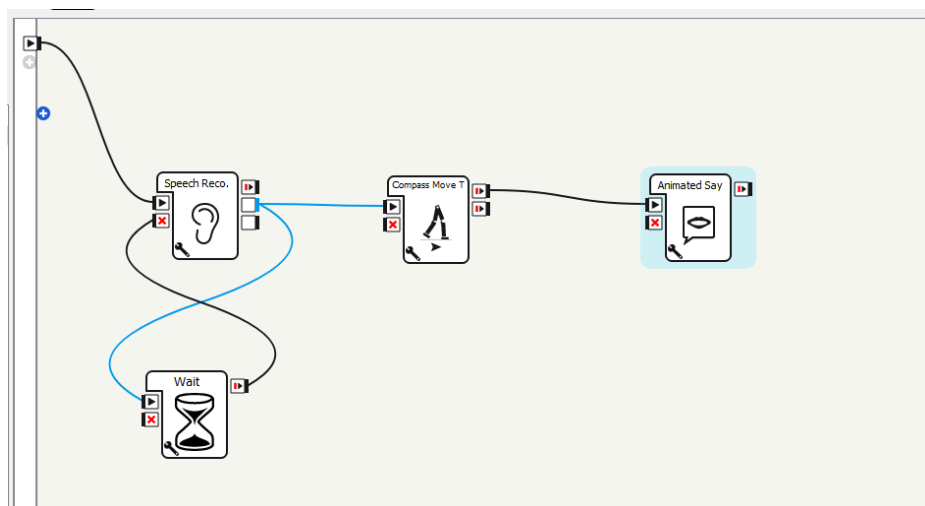
Program the NAO - activity 2

Objective: walk and greet; make the presentation stop

After starting the application, the robot is connected by its IP address. We must click on the navel of the NAO so that it tells us its IP address.



Build the following programming, with the parameters indicated below.



Understand programming



The block (Speech Reco.) does voice recognition and when it hears “Come here”, it sends a command to the next block.



The (Wait) block waits one second and turns off the speech recognition block.



The block (Compass Move To) makes the Robot walk according to the parameters.



The block (Animated Say) allows the Robot to greet us, saying “Hello! How are you?”.